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Aspects of robot driving. An introduction with examples

CHAPTER 1. About Linux

CHAPTER 2. Description of the ATRV-Jr mobile robot

CHAPTER 3. Wireless communications

CHAPTER 4. Performance of built-in SONAR system

CHAPTER 5. The client-server communication architecture

CHAPTER 6. Description of the server

CHAPTER 7. Design of clients with specific tasks

CHAPTER 8. Signal Analysis and Synthesis